

Ch7 The 1st & 2nd variation formula

Let • $M =$ complete Riem mfd.

• $\gamma(t, u): [a, b] \times [-\epsilon, \epsilon] \rightarrow M$ a C^∞ map

• $\{\gamma_u(t)\}$ corresponding 1-parameter family of curves with base curve γ_0 equal to a given curve $\gamma(t)$ parametrized by arc-length, i.e. $|\gamma'(t)| = 1$.

• $U =$ transversal vector field of $\{\gamma_u\}$.

• $T =$ tangent vector field along $\{\gamma_u\}$.

Then the length of $\gamma_u(t)$ is

$$L(u) = \int_a^b |\gamma'_u(t)| dt = \int_a^b |T| dt$$

$$\Rightarrow \frac{dL}{du}(u) = \int_a^b \frac{d}{du} |T| dt$$

$$= \int_a^b U \sqrt{\langle T, T \rangle} dt$$

$$= \int_a^b \frac{\langle T, D_U T \rangle}{|T|} dt$$

$$= \int_a^b \frac{1}{|T|} \langle T, D_T U \rangle dt \quad [T, U] = 0$$

Putting $u=0$,

$$\begin{aligned} \frac{dl}{du}(0) &= \int_a^b \langle \gamma'(t), D_{\gamma'(t)} U \rangle dt \\ &= \int_a^b \left[\frac{d}{dt} \langle \gamma'(t), U \rangle - \langle D_{\gamma'(t)} \gamma'(t), U \rangle \right] dt \end{aligned}$$

where $U(t) = U(t, 0)$ is the transversal vector field along γ .

$$\boxed{\frac{dl}{du}(0) = \langle \gamma'(t), U(t) \rangle \Big|_a^b - \int_a^b \langle D_{\gamma'(t)} \gamma'(t), U(t) \rangle dt}$$

which is the 1st variation formula for arc-length.

Lemma 1: A curve $\gamma: [a, b] \rightarrow M$ is a geodesic \Leftrightarrow
 it is a critical point of the arc-length functional
 with respect to (all) normal variations $\{\gamma_u\}$
 (i.e. $\forall u, \gamma_u(a) = \gamma(a)$ & $\gamma_u(b) = \gamma(b)$.)

Pf: For normal variations, $U(a) = U(b) = 0$

$$\begin{aligned} \therefore \frac{dl}{du}(0) &= - \int_a^b \langle D_{\gamma'} \gamma', U \rangle dt \\ &\quad \forall U \text{ with } U(a) = U(b) = 0. \end{aligned}$$

$$\therefore 0 = \frac{dl}{du}(0) \Leftrightarrow D_{\gamma'} \gamma' = 0 \quad (\text{Ex!})$$

$\forall U$ with $U(a) = U(b) = 0$

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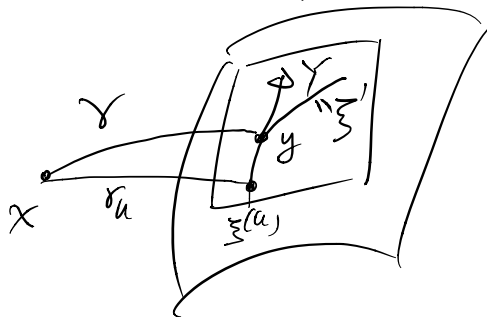
- Lemma 2: Let
- $N =$ closed submanifold of M
 - $x \notin M$
 - $y \in N$ such that $d(x, y) = d(x, N)$
 $\stackrel{\text{def}}{=} \inf\{d(x, y) : y \in N\}$.
 - $\gamma = [a, b] \rightarrow M$ shortest geodesic joining x to y .

Then γ is normal to N (i.e. $\gamma'(b) \perp T_y N$)
 $(\gamma(b) = y)$

Pf: Let $Y \in T_y N$. We need to show that $\langle \gamma'(b), Y \rangle = 0$.

For this, take a C^∞ curve $\xi = [-\varepsilon, \varepsilon] \rightarrow N$

s.t. $\xi'(0) = Y$ ($\xi(0) = y$)



Let $\{\gamma_u\}$ be a 1-parameter family of curves given by

$\gamma(t, u) = [a, b] \times [-\varepsilon, \varepsilon] \rightarrow M$ with

$$\begin{cases} \gamma_0(t) = \gamma(t), & \forall t \in [a, b] \\ \gamma_u(a) = x, & \forall u \\ \gamma_u(b) = \xi(u) \end{cases}$$

By assumption $L(0) = d(x, y) \leq d(x, \xi(u)) \leq L(u), \forall u \in [-\varepsilon, \varepsilon]$

$$\Rightarrow \frac{dL}{du}(0) = 0.$$

1st variation formula \Rightarrow

$$\begin{aligned} 0 &= \langle \gamma'(t), U(t) \rangle \Big|_a^b - \int_a^b \langle D_{\gamma'} \gamma', U \rangle dt \\ &= \langle \gamma'(b), U(b) \rangle - \langle \gamma'(a), U(a) \rangle \\ &= \langle \gamma'(b), U(b) \rangle \quad (\gamma_u(a) \equiv \gamma, \forall u) \end{aligned}$$

By $\gamma_u(b) = \xi(u)$, $\forall u$, we have

$$U(b) = \xi'(0) = Y.$$

$$\therefore 0 = \langle \gamma'(b), Y \rangle. \quad \ast$$

Now suppose that $\gamma: [a, b] \rightarrow M$ is a normalized geodesic.

We would like to calculate $\frac{d^2 L}{du^2}(0)$ for the family $\{\gamma_u\}$.

We've proved that

$$\frac{dL}{du}(u) = \int_a^b \frac{1}{|\dot{\gamma}|} \langle T, D_T U \rangle dt$$

$$\Rightarrow \frac{d^2 L}{du^2}(u) = \int_a^b \frac{\partial}{\partial u} \left[\frac{1}{|\dot{\gamma}|} \langle T, D_T U \rangle \right] dt$$

$$= \int_a^b \left[-\frac{1}{|\dot{\gamma}|^3} \langle T, D_T U \rangle^2 + \frac{1}{|\dot{\gamma}|} U \langle T, D_T U \rangle \right] dt$$

$$= \int_a^b \left[-\frac{1}{|\dot{\gamma}|^3} \langle T, D_T U \rangle^2 + \frac{1}{|\dot{\gamma}|} \langle D_U T, D_T U \rangle + \frac{1}{|\dot{\gamma}|} \langle T, D_U D_T U \rangle \right] dt$$

$$= \int_a^b \left\{ -\frac{1}{|\Pi|^3} \langle T, D_T U \rangle^2 + \frac{1}{|\Pi|} |D_T U|^2 + \frac{1}{|\Pi|} \langle T, D_T D_U U + R_{TU} U \rangle \right\} dt$$

(since $[U, T] = 0$)

$$= \int_a^b \left\{ -\frac{1}{|\Pi|^3} \left[T \langle T, U \rangle - \langle D_T T, U \rangle \right]^2 + \frac{1}{|\Pi|} |D_T U|^2 + \frac{1}{|\Pi|} \langle T, D_T D_U U \rangle - \frac{1}{|\Pi|} \langle R_{UT} U, T \rangle \right\} dt$$

Note that at $u=0$, $\begin{cases} D_T T = D_U \gamma' = 0 \\ |\Pi| = |\gamma'| = 1. \end{cases}$

$$\therefore \frac{d^2 L}{du^2}(0) = \int_a^b \left\{ -\left[\frac{d}{dt} \langle \gamma', U \rangle \right]^2 + |U'|^2 - \langle R_{U\gamma'} U, \gamma' \rangle + \left(\frac{d}{dt} \langle \gamma', D_U U \rangle - \langle D_{\gamma'} \gamma', D_U U \rangle \right) \right\} dt$$

\Rightarrow

$$\boxed{\frac{d^2 L}{du^2}(0) = \langle \gamma', D_U U \rangle \Big|_a^b + \int_a^b \left\{ \left[|U'|^2 - \left(\frac{d}{dt} \langle \gamma', U \rangle \right)^2 \right] - \langle R_{U\gamma'} U, \gamma' \rangle \right\} dt}$$

which is the 2nd variation formula (for normalized geodesic)

Let $U^\perp = U - \langle U, \gamma' \rangle \gamma'$ the normal component of U , then the 2nd variation formula can be written as

$$\frac{d^2 L}{du^2}(0) = \langle r', D_U U \rangle \Big|_a^b + \int_a^b \left\{ |D_{\delta'} U^\perp|^2 - \langle R_{U^\perp \delta'} U^\perp, r' \rangle \right\} dt$$

Note: • If $\{r_u\}$ is normal in the sense that

$$r_u(a) = r(a), \quad r_u(b) = r(b)$$

$$\text{then } \langle r', D_U U \rangle(a) = \langle r', D_U U \rangle(b) = 0$$

• If $\{r_u\}$ is a 1-parameter of (smooth) closed curves, then $\langle r', D_U U \rangle \Big|_a^b = 0$.

• The interior term

$$\int_a^b \left[|D_{\delta'} U^\perp|^2 - \langle R_{U^\perp \delta'} U^\perp, r' \rangle \right] dt$$

is related to the Jacobi Operator on U^\perp (under a suitable bdy condition).

Application 1

Thm 3 Let • $M =$ complete simply-connected Riem. mfd. with

- $K \leq 0$ (sectional curvature)
- $0 \in M$ is a fixed point.
- $\rho: M \rightarrow [0, \infty)$ (the distance function wrt 0) is defined by $\rho(x) = d(x, 0)$.

Then $\rho^2 \in C^\infty(M)$ and $D^2\rho^2 > 0$ (strictly positive definition)

Eg: If $M = \mathbb{R}^n$, $0 = \text{origin}$, then $\rho^2(x) = |x|^2$ and
 $D^2\rho^2(v, v) = c|v|^2$ (for some $c > 0$) (Ex!)

Pf of Thm 3: By Cartan-Hadamard Thm,

$$\rho(x) = |(\exp_0)^{-1}(x)|$$

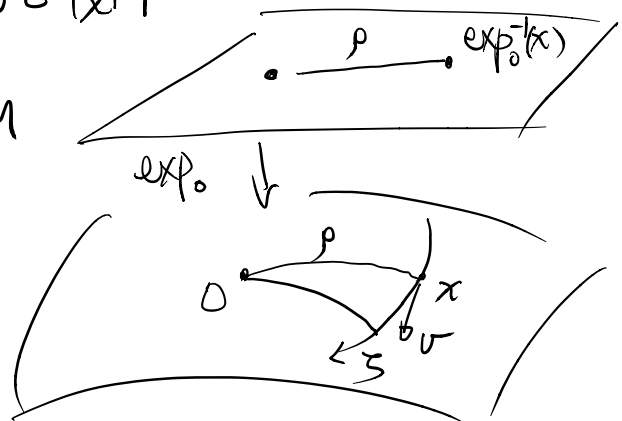
Therefore $\rho^2(x) = |(\exp_0)^{-1}(x)|^2$ is smooth.

Now suppose $x \neq 0$, and $v \in T_x M$

Take a curve $\zeta: [-\varepsilon, \varepsilon] \rightarrow M$

such that

$$\zeta(0) = x \quad \& \quad \zeta'(0) = v$$



For each $u \in [-\varepsilon, \varepsilon]$,

let $\gamma_u = [0, b] \rightarrow M$ (with $b = \rho(x)$, $a = 0$)

is the unique geodesic joining 0 to $\zeta(u)$. Note that

$\gamma_0 = \gamma = [0, b] \rightarrow M$ is a normalized geodesic (other

γ_u may not be normalized.)

Also, we can choose $\zeta(u)$ to be a geodesic. Then

the end point of γ_u is $\gamma_u(b) = \zeta(u)$

\Rightarrow the transversal vector field $U(t, u)$ at $t=b$
is $U(b, u) = \zeta'(u)$.

Therefore $D_U U|_{(b, u)} = D_{\zeta'(u)} \zeta'(u) = 0$ (since $\zeta =$
geodesic)

On the other hand, $\gamma_u(0) = 0 \Rightarrow U(0, u) \equiv 0$

$\Rightarrow D_U U|_{(0, u)} = 0$.

Hence, the 2nd variation formula gives

$$\frac{d^2 L}{du^2}(0) = \int_0^b \left\{ |D_{\gamma'} U^\perp|^2 - \langle R_{U^\perp \gamma'} U^\perp, \gamma' \rangle \right\} dt$$

$$\geq \int_0^b |D_{\gamma'} U^\perp|^2 \quad (\text{since } K \leq 0)$$

$$\text{Now } D^2 \rho^2(\nu, \nu) = \left\{ \zeta'(\zeta' \rho^2) - \cancel{D_{\zeta'} \zeta'} \rho^2 \right\} \Big|_{u=0}$$

$$= \zeta'(\zeta' \rho^2) \Big|_{u=0} \quad (\zeta = \text{geodesic})$$

$$= \zeta'(2\rho \zeta' \rho) \Big|_{u=0}$$

$$= \left[2\rho \zeta'(\zeta' \rho) + 2(\zeta' \rho)^2 \right] \Big|_{u=0}$$

$$= 2\rho(x) \frac{d^2}{du^2} \Big|_{u=0} \rho(\zeta(u)) + 2 \left[\frac{d}{du} \Big|_{u=0} \rho(\zeta(u)) \right]^2$$

Note that $\rho(\gamma(u)) = L(\gamma_u) = L(u)$

$$\begin{aligned} \therefore \frac{d}{du} \Big|_{u=0} \rho(\gamma(u)) &= \frac{dL}{du}(0) \\ &= \langle \gamma'(t), U(t) \rangle \Big|_0^b - \int_a^b \langle \cancel{D_{\gamma'} \gamma'}, U \rangle dt \quad (\text{since } \gamma = \text{geodesic}) \\ &= \langle \gamma'(b), U(b) \rangle \\ &= \langle \gamma'(b), \gamma'(0) \rangle \\ &= \langle \gamma'(b), U \rangle \end{aligned}$$

$$\& \frac{d^2}{du^2} \Big|_{u=0} \rho(\gamma(u)) = \frac{d^2 L}{du^2}(0) \geq \int_0^b |D_{\gamma'} U^\perp|^2 dt$$

$$\therefore D^2 \rho^2(U, U) \geq 2\rho(x) \int_0^b |D_{\gamma'} U^\perp|^2 dt + 2[\langle \gamma'(b), U \rangle]^2$$

If $\langle \gamma'(b), U \rangle \neq 0$, then $D^2 \rho^2(U, U) > 0$.

If $\langle \gamma'(b), U \rangle = 0$, then $U(b) = U \in [\gamma'(b)]^\perp$.

Note that $\{\gamma_u\}$ is a 1-param. family of geodesics,

U is a Jacobi field along γ . Hence

$$\langle \gamma'(b), U(b) \rangle = \langle \gamma'(0), U(0) \rangle = 0 \quad (U(b) = U \neq 0)$$

$\Rightarrow U(t)$ is nontrivial normal Jacobi field

$$\therefore U^\perp(t) = U(t)$$

Therefore $D_{\gamma'} U^\perp = D_{\gamma'} U \neq 0$. Otherwise, U is a

parallel transport of $U(0)=0 \Rightarrow U \equiv 0$ which is a contradiction.

All together, we have $D^2 p^2(U, U) \geq \int_0^b |D_t U|^2 dt > 0$

(for $U \neq 0$). This completes the proof of the thm. ~~✗~~

The key point of the conclusion of the above thm is that $D^2 p^2 > 0$ on the whole M , which needs the curvature assumption. Otherwise, we have

Lemma 4 Let $\bullet M = \text{Riem mfd}$

$\bullet O \in M$

$\bullet \rho: M \rightarrow \mathbb{R}$ distance to O

Then \exists a nbd U_0 of O in M st. ρ^2 is smooth and $D^2 p^2 > 0$ in U_0 .

Sketch of Pf: Let U be a nbd. of O st. \exists normal coordinate system $\{x^1, \dots, x^n\}$ centered at O . Using

this, one can show that $U, w \in T_0 M$,

$$D^2 p^2(U, w) = 2 \langle U, w \rangle \quad (\text{Ex!})$$

Therefore, at the center O , $D^2 p^2 > 0$.

$\Rightarrow D^2 p^2 > 0$ in a nbd $U_0 \subset U$ of O . ~~✗~~

Def: A function $f: M \rightarrow \mathbb{R}$ ($M = \text{Riem. mfd}$)
 is said to be convex (strictly convex)

$\Leftrightarrow \forall$ geodesic γ in M , $f \circ \gamma$ is convex
 (strictly convex).

• Therefore, a C^∞ $f: M \rightarrow \mathbb{R}$ is convex (strictly convex)

$\Leftrightarrow D^2 f \geq 0$ (> 0) (Ex!)

Def: Let $M = \text{complete Riem. mfd}$. Then

• a subset $\Omega \subset M$ is called convex

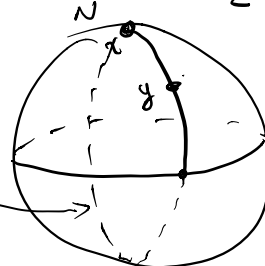
$\Leftrightarrow \forall x, y \in \Omega$, the shortest geodesic joining
 x to y is contained in Ω .

• a subset $\Omega \subset M$ is called totally convex

$\Leftrightarrow \forall x, y \in \Omega$, any geodesic joining x to y
 is contained in Ω .

Eg 1: On $S^2 \subset \mathbb{R}^3$, geodesic ball of radius $r \leq \frac{\pi}{2}$
 is convex, but not totally convex

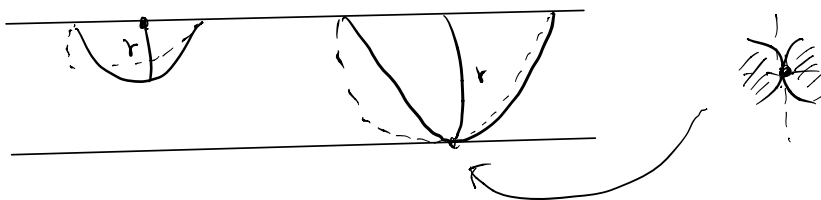
geodesic joining x to y
 not contained in $B_r(x)$



Furthermore, geodesic ball of radius r between $\frac{\pi}{2}$ & π .
 is not even convex (Ex!)

Note: If M is a simply-connected complete Riem. mfd with nonpositive sectional curvature. Then Cartan-Hadamard
 \Rightarrow any geodesic is minimizing. Therefore, a convex subset of M is also totally convex.

Eg 2 Cylinder $\{x^2+y^2=1\} \subset \mathbb{R}^3$. Then B_r is convex
 for $r \leq \frac{\pi}{2}$, not convex for $r > \frac{\pi}{2}$:



Lemma 5 Let $M = \text{Riem mfd}$

(1) Let $\cdot \tau = M \rightarrow \mathbb{R}$ is a convex function

$\cdot M_c \stackrel{\text{def}}{=} \{x \in M : \tau(x) < c\}$ be the sublevel
 set

$\cdot \gamma = [a, b] \rightarrow M$ be a geodesic.

Then $\gamma(a), \gamma(b) \in M_c \Rightarrow \gamma([a, b]) \subset M_c$

(2) Furthermore, if M is complete, then M_c is totally convex.

Pf: (1) $\tau \circ \gamma(t) \leq \max \{ \tau \circ \gamma(a), \tau \circ \gamma(b) \} < c$
 since $\tau \circ \gamma$ convex.

(2) Easily follows from (1).

Cor (of Thm 3) Geodesic balls of a simply-connected complete Riem. mfd M with nonpositive sectional curvature are totally convex.

In particular, $\forall x \in M$, $\{x\}$ is totally convex. Therefore, there is no nontrivial geodesic $\gamma: [a, b] \rightarrow M$ s.t.

$$\gamma(a) = \gamma(b) = x.$$

Thm 6 (J.H.C. Whitehead) Let $M =$ Riem. mfd. Then $\forall x \in M$, \exists a convex nbd. of x .

Pf: $\forall x \in M$, Lemma 4 (& properties of \exp_x)

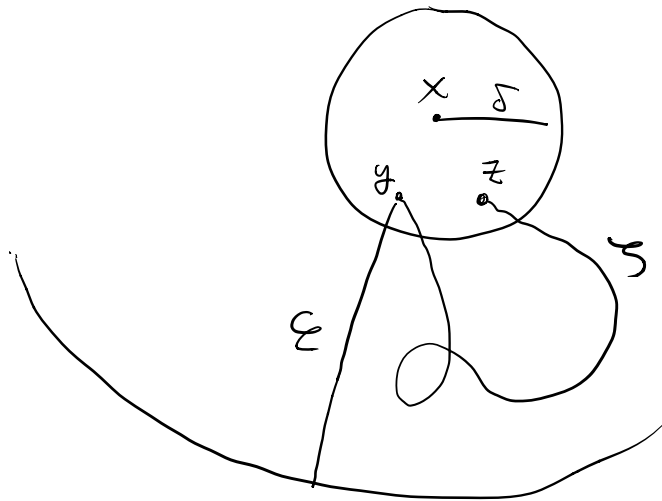
$\Rightarrow \exists \varepsilon > 0$ s.t. $c_{T_x M} \quad c_M$

- $\exp_x: B(\varepsilon) \rightarrow B_\varepsilon(x)$ is a diffeomorphism
- $B_\varepsilon(x) = \exp_x(B(\varepsilon))$ has compact closure in M
 (note: M may not be complete)

1. ρ^2 is C^∞ & $D^2\rho^2 > 0$ on $B_\varepsilon(x)$,
 where $\rho = \text{distance to } x$.

In fact, by choosing a smaller $\varepsilon > 0$, we can also assume
 that $\forall y \in B_\varepsilon(x)$, $\exp_y|_{B(\varepsilon)}$ is a diffeomorphism.

Let $\delta = \frac{\varepsilon}{3} > 0$ and consider the geodesic ball
 $B_\delta(x)$. We claim that $B_\delta(x)$ is convex.



\forall fixed $y \in B_\delta(x)$, we observe that $B_\delta(x) \subset B_\varepsilon(y)$.

In fact, $\forall z \in B_\delta(x)$,

$$d(z, y) \leq d(z, x) + d(x, y) \leq \delta + \delta = 2\delta = \frac{2\varepsilon}{3} < \varepsilon.$$

$$\therefore B_\delta(x) \subset B_\varepsilon(y)$$

Therefore, $\forall z \in B_\delta(x)$, \exists shortest geodesic ζ joining z to y with $\zeta \in B_\varepsilon(y)$ and $L(\zeta) < \varepsilon$.

However, we must have $\zeta \subset B_\varepsilon(x)$.

Otherwise, $y, z \in B_\delta(x) \Rightarrow$

$$L(\zeta) > 2(\varepsilon - \delta) = 2\left(\varepsilon - \frac{\varepsilon}{3}\right) = \frac{4}{3}\varepsilon > \varepsilon$$

which is a contradiction.

Since $D^2\rho^2 > 0$ on $B_\varepsilon(x)$, statement (1) of lemma 5

on $B_\delta(x) (\subset B_\varepsilon(x)) \Rightarrow$

$B_\delta(x) = \text{sublevel set of } \rho^2$

$\Rightarrow \zeta \subset B_\delta(x)$ since ζ is the shortest geodesic joining z to y .

Since $y \in B_\delta(x)$ is arbitrary, we've shown that

$\forall y, z \in B_\delta(x)$, \exists shortest geodesic $\zeta \subset B_\delta(x)$

joining y & z . $\therefore B_\delta(x)$ is convex. ~~XX~~

Application 2: Sygne Thm

Fact: • A C^∞ mfd M of n -dim. is said to be orientable $\Leftrightarrow \exists$ a nowhere zero C^∞ n -form ω on M

(i.e. $\omega = f dx^1 \wedge \dots \wedge dx^n$ in local coordinates:
Alternating $(0,n)$ -tensor = $\omega(X_1, \dots, X_j, \dots, X_j, \dots, X_n)$
= $-\omega(X_1, \dots, X_j, \dots, X_i, \dots, X_n)$)

• If such an ω is chosen, then it is called the orientation of M ($\omega_1 \sim \omega_2 \Leftrightarrow \omega_1 = f \omega_2$ for some function $f > 0$)

• Let ω be a nowhere zero n -form on such an M , then bases of $T_x M$ can be divided into 2-classes:

$\left\{ \begin{array}{l} \bullet \text{ positive oriented: } \omega(e_1, \dots, e_n) > 0 \\ \bullet \text{ negative oriented: } \omega(e_1, \dots, e_n) < 0. \end{array} \right.$

(wrt ω)

Lemma 7: Let $\gamma = [a, b] \rightarrow M$ be a closed curve in an

orientable Riem. mfd M such that $x = \gamma(a) = \gamma(b)$.

Then the parallel transport along γ

$$P^\gamma: T_x M \rightarrow T_x M \text{ has } \det P^\gamma = +1.$$

(Pf. Ex!)

Lemma 8: let $M = \text{non-simply-connected compact Riem mfd. } (\pi_1(M) \neq 1)$

Then \exists closed curve $\gamma: [0, b] \rightarrow M$ (for some $b > 0$)

such that $L(\gamma) \leq L(\alpha)$ for any piecewise C^∞

closed curve α which is non-homotopic to zero

(i.e. $\alpha \neq 1$)

(Pf = Omitted)

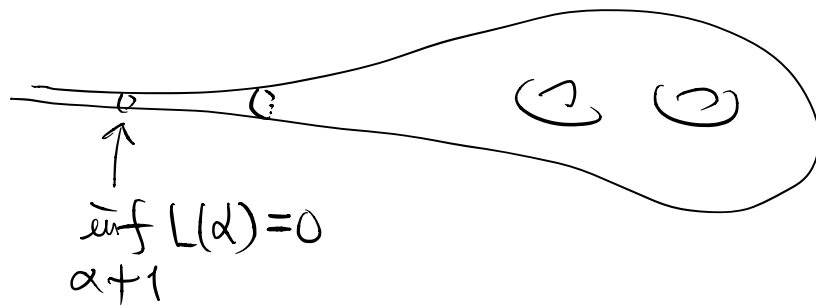
Notes: • $\pi_1(M) \neq 1$ is necessary: ^{otherwise} any closed curve can be shrunk to a point.

$$\Rightarrow \inf_{\gamma} L(\gamma) = 0$$

\Rightarrow no curve minimizes the length functional!

• compactness is also necessary:

eg: surface with a cusp:



Thm 9 (J.L. Synge) If M is a compact orientable
even dim'd Riem. mfd with positive sectional
curvature, then M is simply-connected.

Pf: Suppose not, then $\pi_1(M) \neq 1$.

By Lemma 8, \exists a closed curve $\gamma = [0, b] \rightarrow M$
 st. $L(\gamma) \leq L(\alpha)$, $\forall \alpha \neq 1$.

Then γ has to a geodesic and hence
 $\gamma'(0) = \gamma'(b)$.

We may also assume $|\gamma'(t)| = 1$.

Let $x = \gamma(0) = \gamma(b)$. Then parallel transport along

$$\gamma = P^\gamma = T_x M \rightarrow T_x M$$

has $\det P^\gamma = +1$ (Lemma 7).

Note that eigenvalues of P^γ are of the form $\pm 1, e^{i\theta}$ ($\neq \pm 1$), and if $e^{i\theta}$ is an eigenvalue, then $e^{-i\theta}$ is also an eigenvalue.

Since $\det P^\gamma = +1$, the $\dim\{-1 \text{ eigenspace}\}$ is even.
Hence $\dim M = \text{even} \Rightarrow \dim\{+1 \text{ eigenspace}\}$ is also even.

Note that γ is a closed geodesic, $\gamma'(0) = \gamma'(b)$

$$\& \quad P^\gamma(\gamma'(0)) = \gamma'(b) = \gamma'(0)$$

$$\Rightarrow \dim\{+1 \text{ eigenspace}\} > 0, \text{ hence } \geq 2.$$

Therefore, $\exists e \in T_x M$ s.t. $P^\gamma(e) = e$
and $\langle e, \gamma'(0) \rangle = 0$.

Now, let U be the parallel vector field along γ such that $U(0) = e$.

$$\text{Then } U(b) = P^\gamma(U(0)) = P^\gamma(e) = e$$

$\Rightarrow U$ is well-defined vector field on the closed curve γ .

$\Rightarrow \exists$ a 1-parameter family of closed geodesics

$\{\gamma_u\}$ s.t. $\gamma_0 = \gamma$ & $U =$ transversal vector field of $\{\gamma_u\}$ ($\gamma_u(t) = \exp_{\gamma(t)}(uU(t)), |u| \leq 1$).

Then 2nd variation formula \Rightarrow

$$\frac{d^2 L}{du^2}(0) = \int_0^b \left[|D_{\gamma'} U^\perp|^2 - \langle R_{\gamma'} U^\perp \gamma', U^\perp \rangle \right] dt$$

(since γ_u closed $\forall u \Rightarrow$ bdy term = 0)

Since $\langle U(0), \gamma'(0) \rangle = \langle e, \gamma'(0) \rangle = 0$, we have

$$U^\perp = U, \quad \forall t \in [0, b]$$

$$\Rightarrow D_{\gamma'} U^\perp = D_{\gamma'} U = 0 \quad (\text{since } U \text{ parallel})$$

$$\therefore \frac{d^2 L}{du^2}(0) = - \int_0^b \langle R_{\gamma'} U^\perp \gamma', U^\perp \rangle dt < 0$$

(since sectional curvature > 0)

Contradicting that γ is length minimizing.

$$\therefore \pi_1(M) = 1. \quad \times$$